

## When Collaborative Information is Not Enough

Evgeny Frolov<sup>1</sup>, Research Scientist  
 Ivan Oseledets<sup>1,2</sup>, Associate Professor

<sup>1</sup>Skolkovo Institute of Science and Technology  
<sup>2</sup>Institute of Numerical Mathematics of the Russian Academy of Sciences

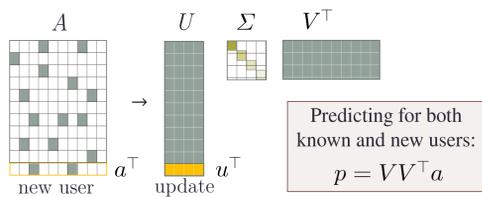
### 1. BACKGROUND

Proper tuning of simpler baselines vs. modern SOTA shows surprising results.  
 Part of the reason – tuning can be hard and cumbersome!  
 Can we reduce tuning hassles at least for the baselines?

Example: PureSVD  $\|A - U\Sigma V^T\|_F^2 \rightarrow \min$

Advantages:

- ✓ simple tuning via rank truncation
  - ✓ minimal storage requirements
  - ✓ supports real-time & session-based recs
  - ✓ stable, deterministic output
  - ✓ highly optimized implementations
  - ✓ scales to ~billion-size problems
- e.g., <https://github.com/criteo/Spark-RSVD>



Data-debiasing trick [Nikolakopoulos et al. 2019]:

- $$A \leftarrow AD^{d-1} \quad D = \text{diag}\{\|a_1\|, \dots, \|a_N\|\}$$
- $\uparrow d$  emphasizes the significance of popular items,
  - $\downarrow d$  improves sensitivity to rare/niche items,
  - often leads to a significant quality improvement.

Interesting fact: the 3rd most cited work (via Scopus) among all ACM RecSys conference proceedings papers!

### 2. OBJECTIVES

To develop efficient LRA method that

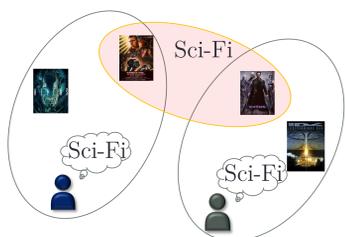
- allows incorporating side information into the model,
- inherits the key advantages of the PureSVD approach,
- admits minimal tuning,
- outperforms strong baselines in typical tasks.

### 3. KEY IDEA

“Similarity” of users  $i$  and  $j$  depends on co-occurrence of items in their preferences.

$$G = AA^T = U\Sigma^2U^T \leftrightarrow g_{ij} = a_i^T a_j \sim \text{sim}(i, j)$$

Replace scalar products with a bilinear form.



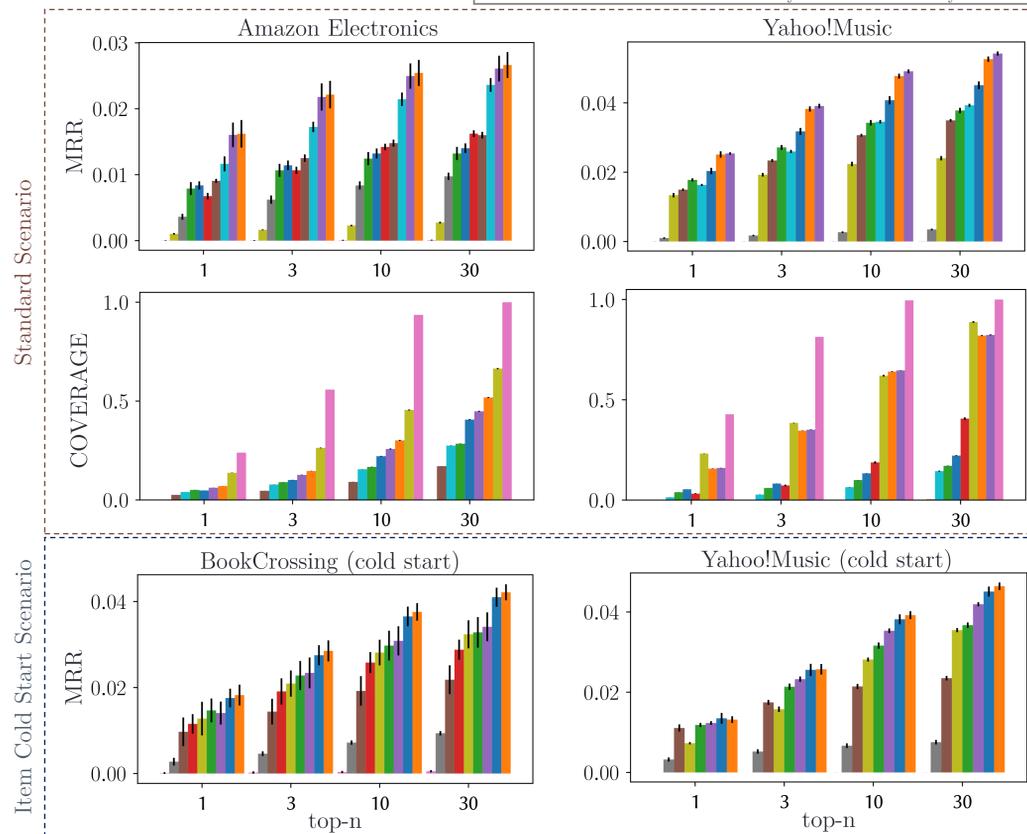
$\text{sim}(i, j) \sim a_i^T S a_j$   
 Creates “virtual” links based on side features.

Similarity matrix  $S$

1			
	1	0.5	
	0.5	1	
			1

### 7. RESULTS

- 5-fold cross-validation (averaged);
- 95% confidence intervals (vertical black bars).



Polara + binder = Reproducibility in browser!

Play with it on your own (no setup required), visit the link below for further instructions: [https://github.com/evfro/recsys19\\_hybridsvd](https://github.com/evfro/recsys19_hybridsvd)  
 Polara – open-source recsys framework for quick and reproducible experimentation. (Note: I’m the author.) <https://github.com/evfro/polara>

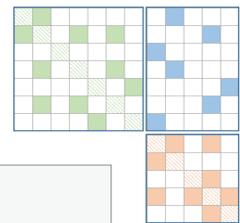
### 4. SOLUTION

The problem takes generalized form:

$$\begin{cases} AA^T = U\Sigma^2U^T \\ A^T A = V\Sigma^2V^T \end{cases} \Rightarrow \begin{cases} ASA^T = U\Sigma^2U^T \\ A^T KA = V\Sigma^2V^T \end{cases}$$

Matrix “roots”:

$$\begin{cases} S = L_S L_S^T \\ K = L_K L_K^T \end{cases}$$



Solution:

via SVD of an auxiliary matrix: [Abdi 2007; Allen/Grosenick/Taylor 2014]

$$L_K^T A L_S = U \Sigma V^T$$

$$\text{link to the original latent space: } L_K^{-T} U = U, \quad L_S^{-T} V = V$$

Properties:

$$\text{latent space structure: } U^T K U = I, \quad V^T S V = I$$

$$\text{“hybrid” folding-in: } p = L_S^{-T} V V^T L_S^T a$$

+ everything from standard SVD

Controlling side features weight and similarity structure:

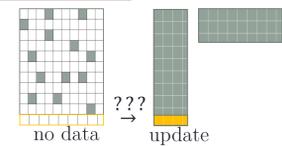
$$\begin{cases} S = (1 - \alpha)I + \alpha Z, \\ K = (1 - \beta)I + \beta W. \end{cases} \quad \begin{cases} Z, W \text{ are real symmetric matrices, } -1 \leq z_{ij}, w_{ij} \leq 1 \quad \forall i, j; \\ 0 \leq \alpha, \beta \leq 1 \quad \text{control how sensitive the model is to side features.} \\ \alpha = \beta = 0 \quad \text{turns the model back into PureSVD.} \end{cases}$$

### 5. ADDRESSING COLD START

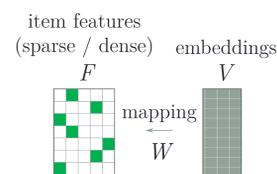
Finding a transformation between latent and real features is a hard task.  
 Hybrid MF models often incorporate this task into main optimization.

Several representative examples:

- Collective factorization [Singh/Gordon 2008, Acar/Kolda/Dunlavy 2011],
- Local Collective Embeddings (LCE) [Saveski/Mantrach 2014],
- Factorization Machines (FM) [Rendle 2010].



It is a lot simpler with SVD!



Using the S-orthogonality property:

$$VW = F \rightarrow W = V^T S F$$

Given any feature vector  $f$ , we can find the corresponding embedding  $v$ :  
 $W^T v = f$

Predicted relevance scores:  
 $p = U \Sigma v = A V v$

Works for PureSVD!  
 (set  $S = I, K = I$ )

### 6. EFFICIENT COMPUTATIONS

Overall computational complexity:  $O(\text{nnz}_A \cdot r) + O((M + N) \cdot r^2) + O((J_K + J_S) \cdot r)$   
 “matvec” complexities for  $L_K$  and  $L_S$

Finding Cholesky/square root factors:

- efficient schemes for sparse and dense representations;
- computational complexity is adjustable, depends on data structure;
- can be computed on GPU <https://developer.nvidia.com/cholmod>.

For sparse feature representations:

- symbolic Cholesky decomposition, can reuse sparsity pattern for different  $\alpha$  and  $\beta$ .
- can also use incomplete or thresholded variant of Cholesky decomposition

For dense feature representations:

- fast symmetric factorization for computing matrix square root [Ambikasaran/O’Neil/Singh 2014].

### 8. CONCLUSIONS

HybridSVD offers a set of practical advantages:

- Allows generating structured latent feature space.
- Has a small number of intuitive hyper-parameters.
- Enables simplified tuning.
- Supports quick online and session-based recommendations.
- Effective in standard, warm start, and cold start regimes.

May not be the best in all cases; however, definitely is a strong baseline!

### 9. SOME REFERENCES

Improving PureSVD with EigenRec model:

Nikolakopoulos, A. N., Kalantzis, V., Gallopoulos, E., & Garofalakis, J. D. (2019). EigenRec: generalizing PureSVD for effective and efficient top-N recommendations. *Knowledge and Information Systems*, 58(1), 59-81.

A structural view on generalized SVD:

Allen, G. I., Grosenick, L., & Taylor, J. (2014). A generalized least-square matrix decomposition. *Journal of the American Statistical Association*, 109(505), 145-159.